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8254 is a device designed to solve the timing control problems in a microprocessor. It has 3 independent counters, each capable of handling clock inputs up to 10 MHz and size of each counter is 16 bit. It operates in +5V regulated power supply and has 24 pin signals. All modes are software programmable.

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The microprocessor is what does the heavy lifting in a computer. It performs the instructions and calculations that make the computer work. Microprocessors are much faster than microcontrollers, but they need external resources like RAM, Input/Output ports, etc., whereas a microcontroller is typically self-contained.

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Maybe this microcontroller has two hardware UART interfaces and 1 SPI interface. If I don't need any UART but instead need a CANBUS interface that microcontroller won't work for me. Sure I can bitbang the protocol on GPIO ports but that uses up a lot of the limited processing power on the microcontroller...

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I'm debugging a piece of (embedded) software. I've set a breakpoint on a function, and for some reason, once I've reached that breakpoint and continue I always come back to the function (which is an initialisation function which should only be called once). When I remove the breakpoint, and continue, GDB tells me: Program received signal SIGTRAP, Trace/breakpoint trap.

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